

# Data and Text Mining

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[https://kt.ijs.si/blaz\\_skrlj/teaching/dmkd2023/#materials](https://kt.ijs.si/blaz_skrlj/teaching/dmkd2023/#materials)

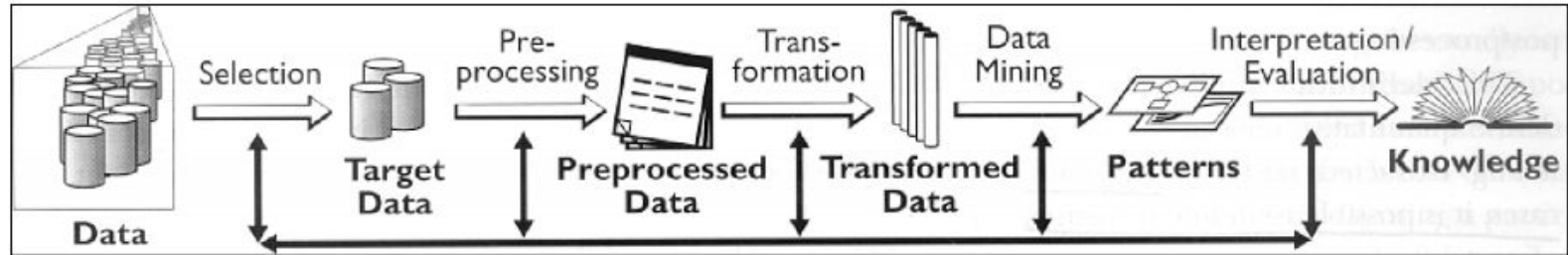


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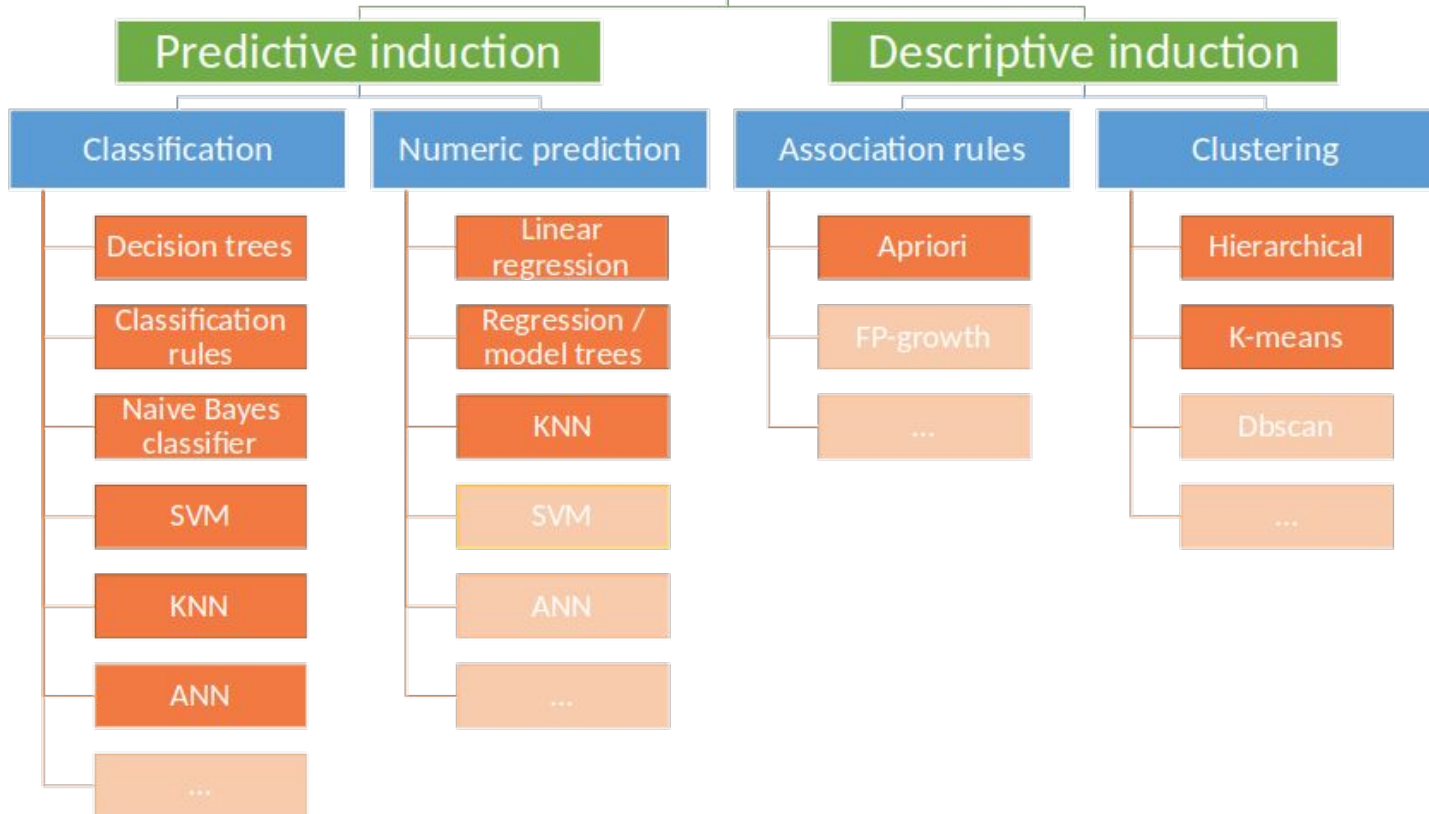
# Overview

- Hands-on Orange3
  - Machine learning and Data Visualization
  - Interactive Analysis
  - **Visual Programming**
  
- Main goals
  - Understanding of the **data mining process**
  - Being able to perform analysis on your own
  - Critical evaluation of the results

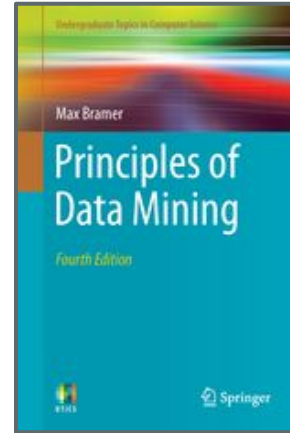
# KDD vs. ML/DM



# Data mining techniques



# Max Bramer: Principles of data mining (2007)



# Attribute Types

## 1. Categorical

- a. Nominal (e.g., Colors -> R,G,B)
- b. Binary (e.g., class presence -> yes, no)
- c. Ordinal (e.g., Size -> small, medium, large, ...)

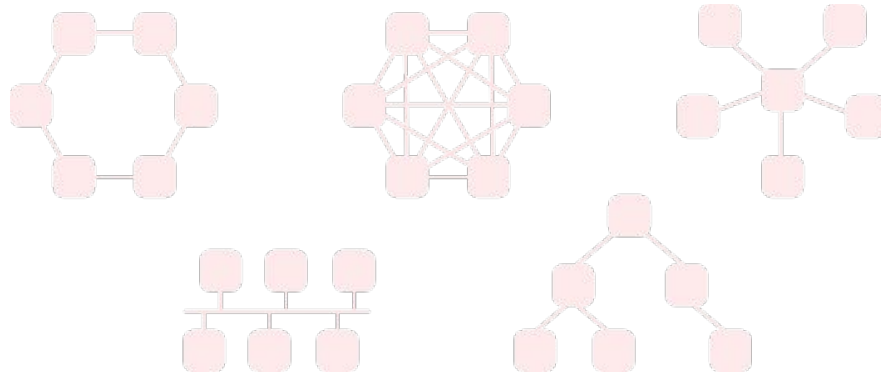
## 2. Numerical

- a. Integer (Number of pets)
- b. Real (wavelength, temperature etc.)

Why is this relevant?

# Complex data types

1. Time series - *data in time*
2. Texts - *instances are documents*
3. Graphs - *instances are related (explicitly)*
4. Images - *instances are images*
5. Multi-modal data - *combined spaces*



# Classification



# The classification problem

- Given a collection of examples, assign them to categories.
  - Magazine reader (or not)
  - A patient at risk of falling ill
  - Likely buyers
  - Types of plants
  - Gene functions

# More formally

1. Given a collection of instances  $X$  with corresponding labels  $Y$ , identify  $f: X \rightarrow Y$ .
  - a. Instances are described by attributes
  - b. The target variable is an attribute we are interested in (e.g., illness, categorical)
  - c. The values of the target variable are called labels.
  - d. The goal is to assign labels to new instances, as accurately as possible.

attributes

(nominal)  
target  
variable

Examples  
or  
instances

Person	Age	Prescription	Astigmatic	Tear Rate	Lenses
P1	young	myope	no	normal	YES
P2	young	myope	no	reduced	NO
P3	young	hypermetrope	no	normal	YES
P4	young	hypermetrope	no	reduced	NO
P5	young	myope	yes	normal	YES
P6	young	myope	yes	reduced	NO
P7	young	hypermetrope	yes	normal	YES
P8	young	hypermetrope	yes	reduced	NO
P9	pre-presbyopic	myope	no	normal	YES
P10	pre-presbyopic	myope	no	reduced	NO
P11	pre-presbyopic	hypermetrope	no	normal	YES
P12	pre-presbyopic	hypermetrope	no	reduced	NO
P13	pre-presbyopic	myope	yes	normal	YES
P14	pre-presbyopic	myope	yes	reduced	NO
P15	pre-presbyopic	hypermetrope	yes	normal	NO
P16	pre-presbyopic	hypermetrope	yes	reduced	NO
P17	presbyopic	myope	no	normal	NO
P18	presbyopic	myope	no	reduced	NO
P19	presbyopic	hypermetrope	no	normal	YES
P20	presbyopic	hypermetrope	no	reduced	NO
P21	presbyopic	myope	yes	normal	YES
P22	presbyopic	myope	yes	reduced	NO
P23	presbyopic	hypermetrope	yes	normal	NO
P24	presbyopic	hypermetrope	yes	reduced	NO

classes  
=  
values of  
the  
(nominal)  
target  
variable

# The basic classification schema

Si	Attrb1	Attrb2	Attrb3	Class
1	Yes	Large	125K	No
2	No	Medium	100K	No
3	No	Small	70K	No
4	Yes	Medium	120K	No
5	No	Large	95K	Yes
6	No	Medium	60K	No
7	Yes	Large	220K	No
8	No	Small	90K	Yes
9	No	Medium	75K	No
10	No	Small	90K	Yes

Training set

Si	Attrb1	Attrb2	Attrb3	Class
11	No	Small	85K	?
12	Yes	Medium	80K	?
13	Yes	Large	110K	?
14	No	Small	65K	?
15	No	Large	67K	?

Testing set



Learning algorithm  
(Learner)



Classification model  
(Classifier)



Predictions



- A classifier is a function that maps from the attributes to the classes
  - $\text{Classifier}(\text{attributes}) = \text{Classes}$
  - $f(X) = Y$
- In training, the attributes and the classes are known (training examples) and we are learning a mapping function  $f$  (the classifier)
  - $?(X) = Y$
- When predicting, the attributes and the classifier are known and we are assigning the classes
  - $f(X) = ?$
- What about evaluation?

# The basic classification schema

Sr	Attr01	Attr02	Attr03	Class
1	Yes	Large	125K	No
2	No	Medium	190K	No
3	No	Small	70K	No
4	Yes	Medium	120K	No
5	No	Large	90K	Yes
6	No	Medium	60K	No
7	Yes	Large	220K	No
8	No	Small	80K	Yes
9	No	Medium	75K	No
10	No	Small	90K	Yes

Training set

Sr	Attr01	Attr02	Attr03	Class
11	No	Small	50K	?
12	Yes	Medium	80K	?
13	Yes	Large	110K	?
14	No	Small	60K	?
15	No	Large	67K	?

Testing set



Learning algorithm  
(Learner)



Classification model  
(Classifier)



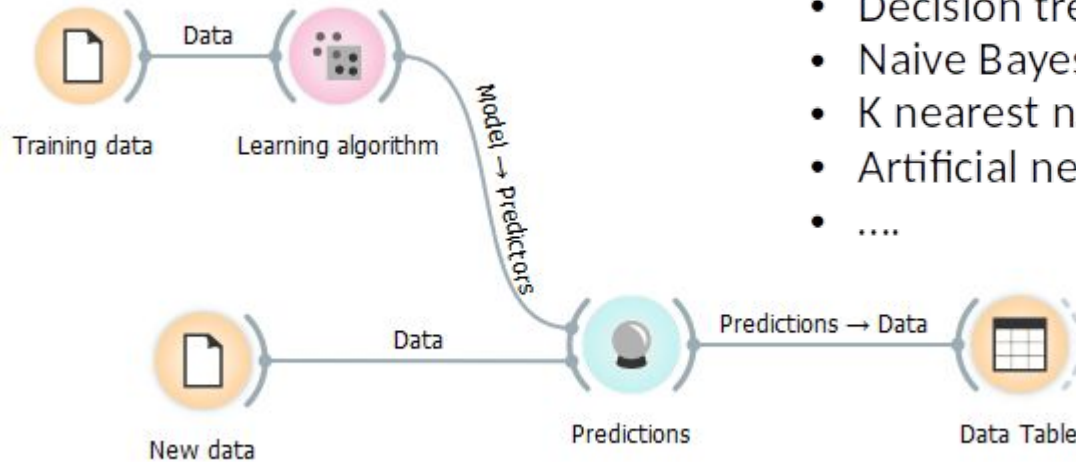
Predictions



- A classifier is a function that maps from the attributes to the classes
  - Classifier(attributes) = Classes
  - $f(X) = Y$
- In training, the attributes and the classes are known (training examples) and we are learning a mapping function  $f$  (the classifier)
  - $?(X) = Y$
- When predicting, the attributes and the classifier are known and we are assigning the classes
  - $f(X) = ?$
- When evaluating,  $f$ ,  $X$  and  $Y$  are known. We compute the predictions  $Y_p = f(X)$  and evaluate the difference between  $Y$  and  $Y_p$ .

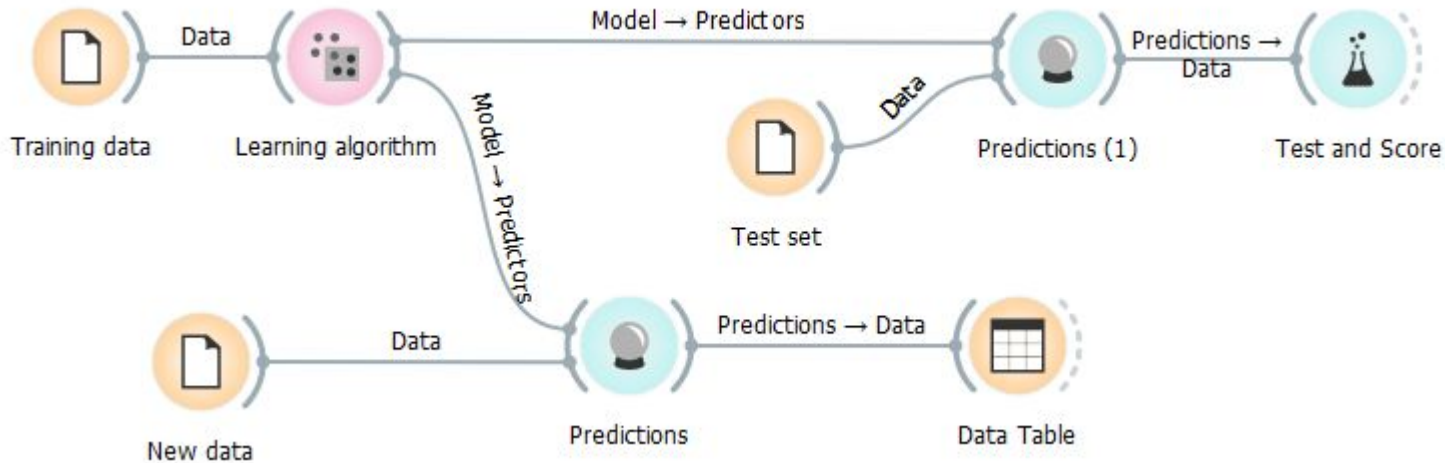
# Basic classification schema

- We train the model on the train set
- We predict the target for the new instances
- There are several classification algorithms:
  - Decision trees
  - Naive Bayes classifier
  - K nearest neighbors (KNN)
  - Artificial neural networks (ANN)
  - ....



# What about evaluation

- We train the model on the train set
- We evaluate on the test set
- We classify the new instances



# A recap

Target variable

Descriptive variables

Examples

	survived	status	age	sex
1281	no	third	child	male
1282	no	third	child	male
1283	no	third	child	male
1284	no	third	child	male
1285	no	third	child	male
1286	yes	third	child	female
1287	yes	third	child	female
1288	yes	third	child	female
1289	yes	third	child	female
1290	yes	third	child	female
1291	yes	third	child	female
1292	yes	third	child	female
1293	yes	third	child	female
1294	yes	third	child	female
1295	yes	third	child	female
1296	yes	third	child	female
1297	yes	third	child	female
1298	yes	third	child	female
1299	yes	third	child	female
1300	no	third	child	female

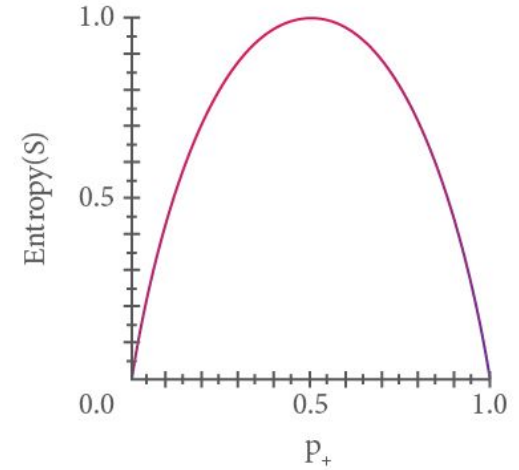


# Algorithm 1: Decision trees

# Trees: Algorithmic background

Induce a decision tree on set  $S$ :

1. Compute the **entropy**  $E(S)$  of the set  $S$
2. **IF**  $E(S) = 0$
3. The current set is “clean” and therefore a leaf in our tree
4. **IF**  $E(S) > 0$
5. Compute the **information gain** of each attribute  $\text{Gain}(S, A)$
6. The attribute  $A$  with the highest information gain becomes the root
7. Divide the set  $S$  into subsets  $S_i$  according to the values of  $A$
8. Repeat steps 1-7 on each  $S_i$



<https://www.hackerearth.com/practice/machine-learning/machine-learning-algorithms/ml-decision-tree/tutorial/>

# Decision Trees - intuition - Information Gain

set S      attribute A

$$Gain(S, A) = E(S) - \sum_{v \in Values(A)} \frac{|S_v|}{|S|} \cdot E(S_v)$$

Entropy of the set S

number of examples in the subset  $S_v$   
(probability of the branch)

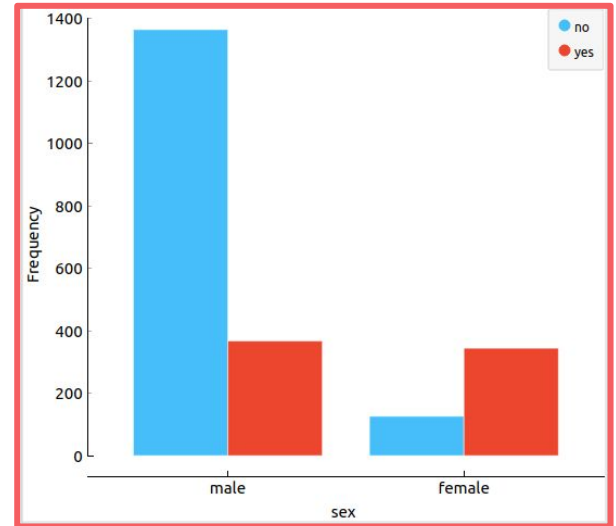
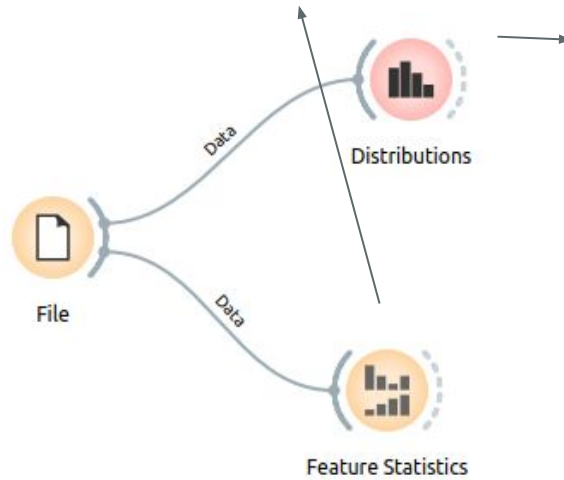
number of examples in set S

Entropy of the subset  $S_v$

# Warm up

Name	Distribution	Mean	Median	Dispersion	Min.	Max.	Missing
status			crew	1.28			0 (0%)
age			adult	0.197			0 (0%)
sex			male	0.519			0 (0%)
survived			no	0.629			0 (0%)

Select: titanic.tab



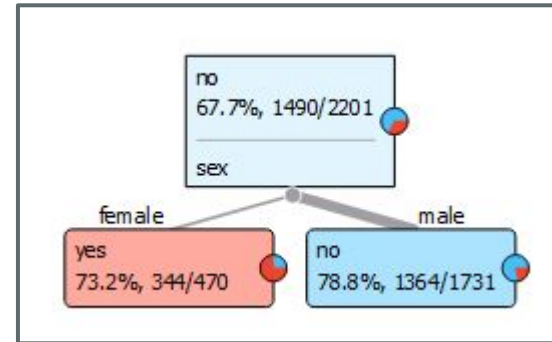
# Illustrative example (IG)

1. Compute entropy of the entire set
2. Identify subsets based on a given attribute's values
3. Compute entropy of each subset
4. Compute the IG

Higher gain = better!

	NO	YES	total
	1490	721	2211
class probability	0.674	0.326	
$\pi \cdot \log(\pi, 2)$	-0.384	-0.527	
entropy	0.911		

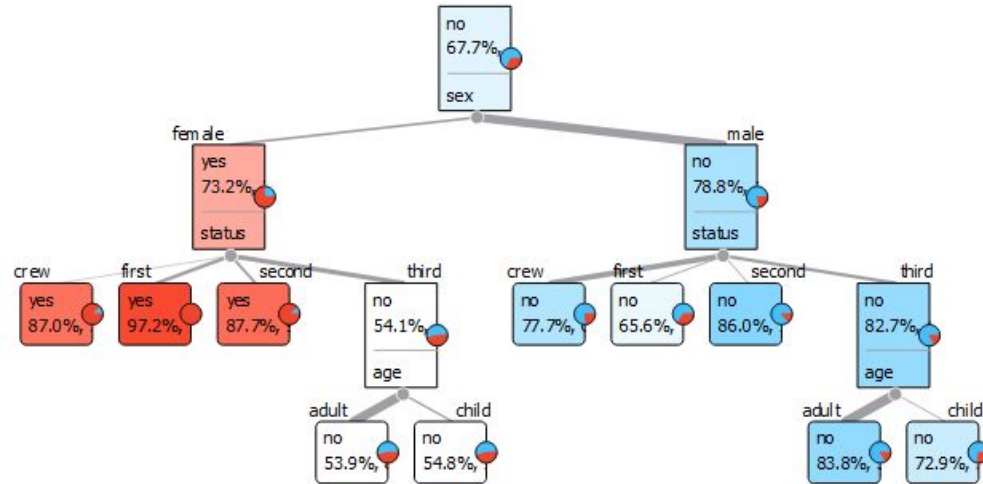
female	NO	YES	total
	136	334	470
Class probability $\pi$	0,289	0,711	
$\pi \cdot \log(\pi, 2)$	-0,52	-0,35	
entropy	0,868		
male	NO	YES	total
	1364	367	1731
Class probability $\pi$	0,788	0,212	
$\pi \cdot \log(\pi, 2)$	-0,27	-0,47	
entropy	0,745		



$$Gain(S, A) = E(S) - \sum_{v \in \text{Values}(A)} \frac{|S_v|}{|S|} \cdot E(S_v)$$

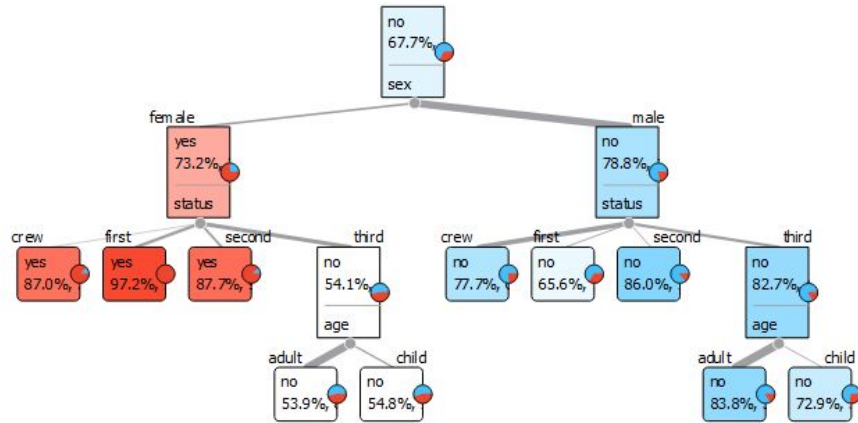
$$Gain(S, Sex) = 0,911 - \left( \frac{470}{2201} \cdot 0,868 + \frac{1731}{2201} \cdot 0,745 \right) = 0,166$$

# Classification via traversal



	status	age	sex	survived?
1	third	child	male	
2	third	child	female	
3	crew	adult	male	
4	first	adult	male	
5	second	adult	male	
6	third	adult	male	
7	first	adult	female	
8	second	adult	female	
9	third	adult	female	
10	third	child	male	

# From trees to rules

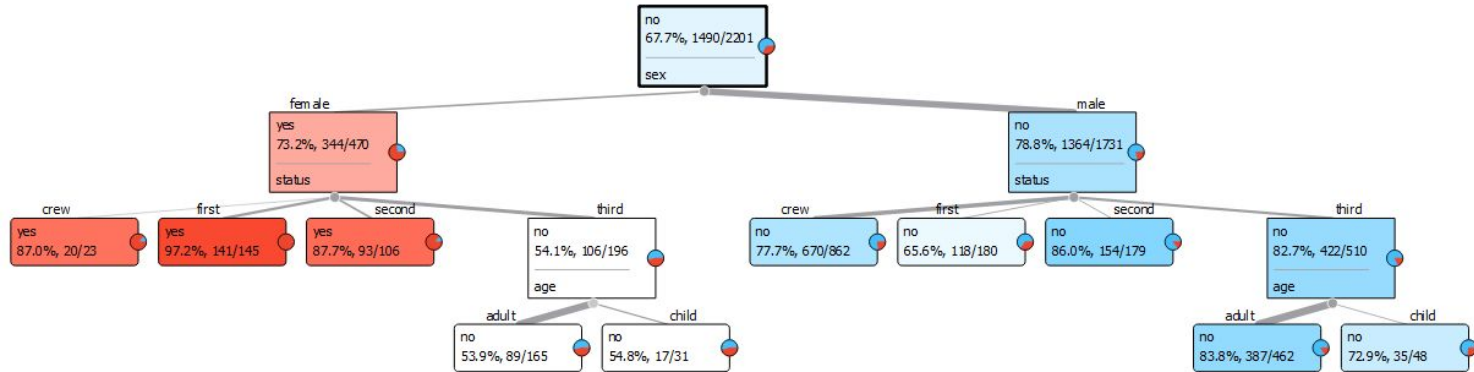


- sex = female & status = crew  $\Rightarrow$  survived = yes
- sex = female & status = first  $\Rightarrow$  survived = yes
- sex = female & status = second  $\Rightarrow$  survived = yes
- sex = female & status = third & age = adult  $\Rightarrow$  survived = no
- sex = female & status = third & age = child  $\Rightarrow$  survived = no
- sex = male & status = crew  $\Rightarrow$  survived = no
- sex = male & status = first  $\Rightarrow$  survived = no
- sex = male & status = second  $\Rightarrow$  survived = no
- sex = male & status = third & age = adult  $\Rightarrow$  survived = no
- sex = male & status = third & age = child  $\Rightarrow$  survived = no

One example -> one rule -> one path!

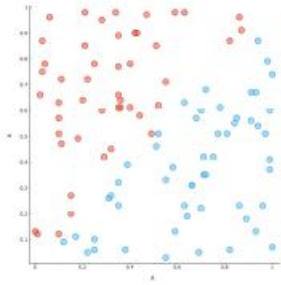
# A note on interpretability

- Attribute importance and its placement
- Visualization interpretation

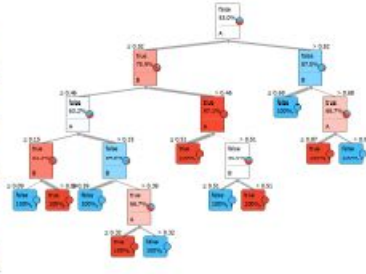




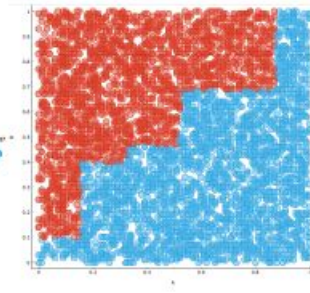
# A note on language bias



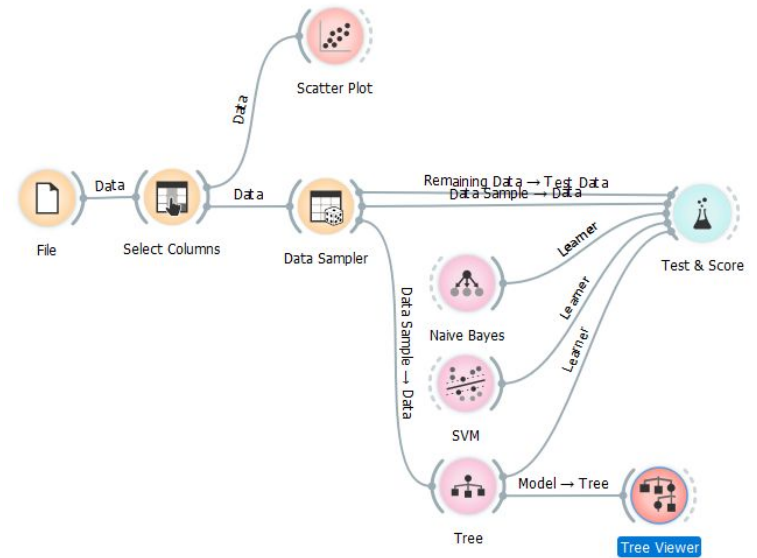
Training set



Decision tree



Test set



# Algorithm 2: Rules

# CN2 Rule Induction

- Based on the “covering” principle
- Dependent on the BEST\_CPX
  - Generates candidate rules
  - Tests their “significance”
  - Prunes the complex space
- Why is this different to tree chopping?
  - Not as greedy
  - Effectively upgrades a rule list

**Let:** E be a set of training examples;

**Procedure** CN2(E) **returning** RULE\_LIST:

let RULE\_LIST be the empty list;

**repeat**

let BEST\_CPX be Find\_Best\_Complex(E);

**if** BEST\_CPX is not nil **then**

Let E' be the examples covered by BEST\_CPX;

Remove from E the examples E' covered by BEST\_CPX;

Let C be the most common class of examples in E';

Add the rule 'if BEST\_CPX then class=C' to the end of RULE\_LIST,

**until** BEST\_CPX is nil **or** E is empty.

**return** RULE\_LIST.

**Procedure** Find\_Best\_Complex(E) **returning** BEST\_CPX:

let the set STAR contain only the empty complex;

let BEST\_CPX be nil;

let SELECTORS be the set of all possible selectors;

**while** STAR is not empty,

specialize all complexes in STAR as follows:

let NEWSTAR be the set  $\{x \wedge y | x \in \text{STAR}, y \in \text{SELECTORS}\}$ ;

Remove all complexes in NEWSTAR that are either in STAR (i.e., the unspecialized ones) or are null (e.g.  $\text{big} = y \wedge \text{big} = \text{n}$ )

**for** every complex  $C_i$  in NEWSTAR:

**if**  $C_i$  is statistically significant when tested on E **and** better than

BEST\_CPX according to user-defined criteria when tested on E,

**then** replace the current value of BEST\_CPX by  $C_i$ ;

**repeat** remove worst complexes from NEWSTAR

**until** size of NEWSTAR is  $\leq$  user-defined maximum;

let STAR be NEWSTAR;

**return** BEST\_CPX.

# Practice time - basic tree learning

1. Open Orange3
2. Load the data
3. Explore the data
4. Build and visualize a tree
5. Generate rules (CN2)



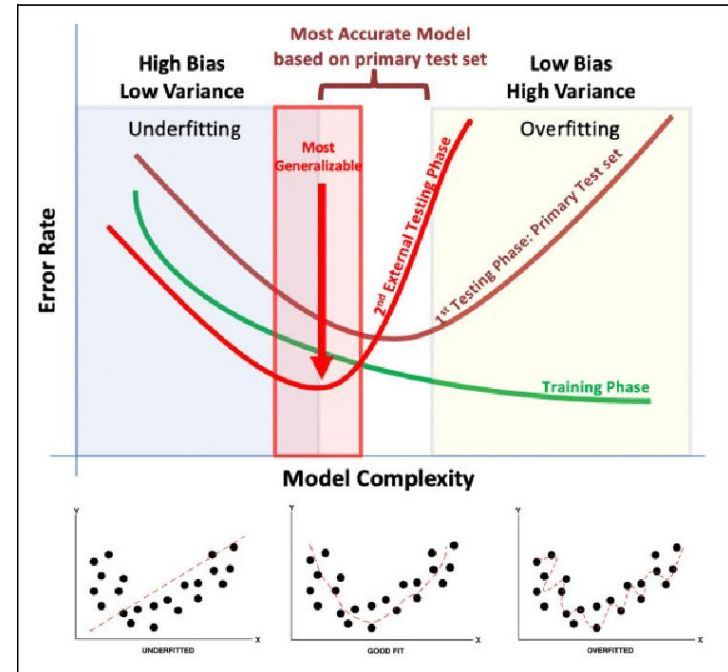
# HW questions

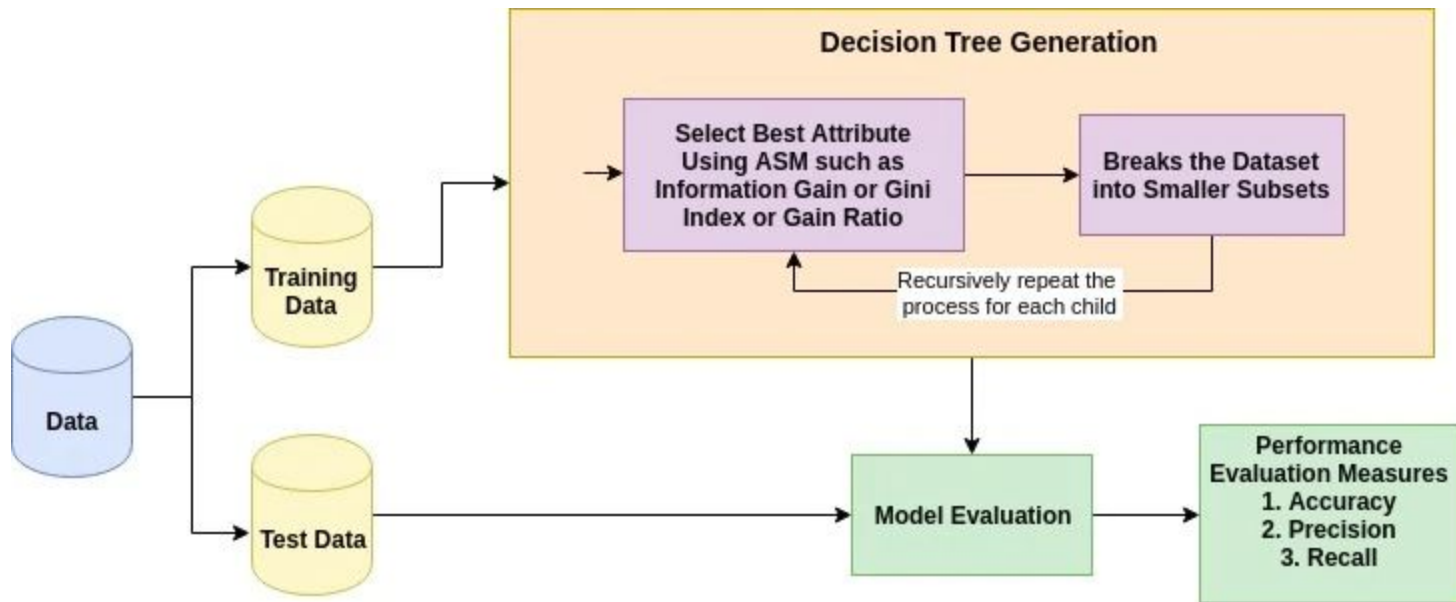
1. How does an attribute with  $IG \approx 1$  look like?
2. What about  $IG \approx 0$ ?
3. How would you compute the information gain of a numeric attribute (Hint: See Kullback-Leibler Divergence)
4. Explain the difference between TDIDT- and CN2-based rules.
  - a. How they are constructed
  - b. How much time does it take to construct them (based on pseudocode)
  - c. Are some more greedy than others? Why?

# Evaluation

# (over) Fitting a model on the whole data set is ... not ok.

- Does the model generalize?
- How do we measure the performance?
- What are we measuring, really?







# Key take-away message

## Test on a separate test set

Person	Age	Prescription	Astigmatic	Tear_Rate	Lenses
P1	young	myope	no	normal	YES
P2	young	myope	no	reduced	NO
P3	young	hypermetrope	no	normal	YES
P4	young	hypermetrope	no	reduced	NO
P5	young	myope	yes	normal	YES
P6	young	myope	yes	reduced	NO
P7	young	hypermetrope	yes	normal	YES
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P18	presbyopic	myope	no	reduced	NO
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P20	presbyopic	hypermetrope	no	reduced	NO
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P22	presbyopic	myope	yes	reduced	NO
P23	presbyopic	hypermetrope	yes	normal	NO
P24	presbyopic	hypermetrope	yes	reduced	NO

30% of examples are  
(randomly)  
selected for testing

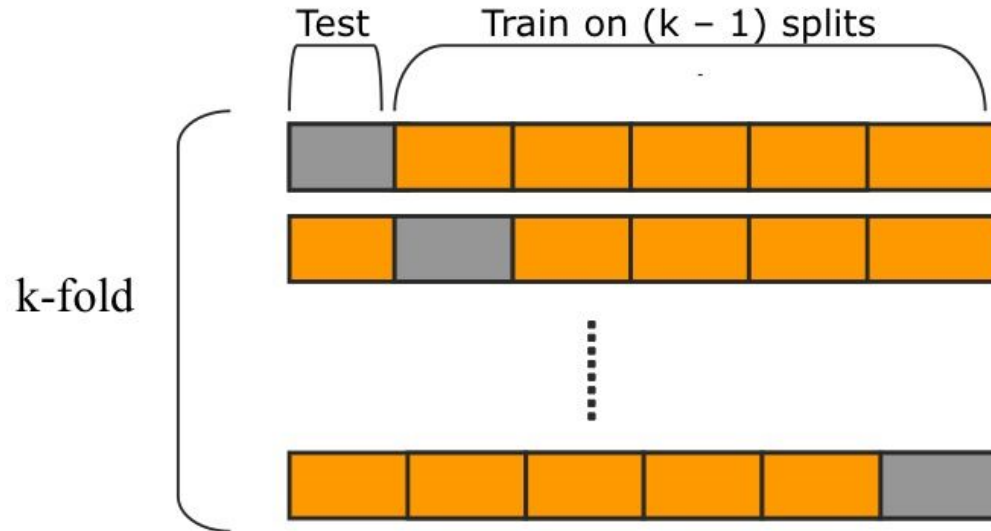


# Common evaluation scenarios

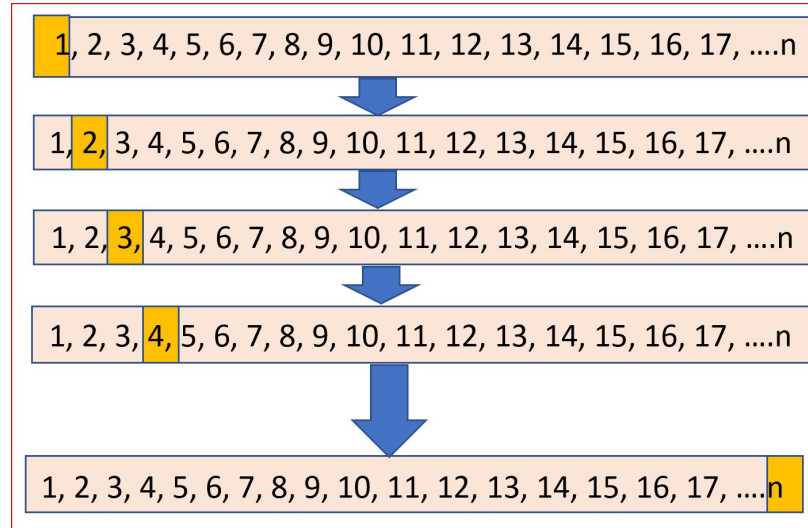
1. Train-val-test split
2. K-fold cross validation
3. Leave-one-out validation
4. Random sampling (and averaging)
5. Stratified splits



# K-fold Cross Validation

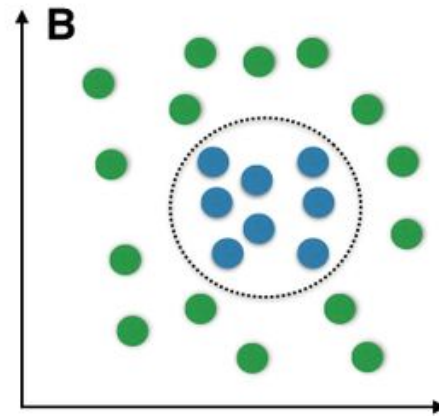
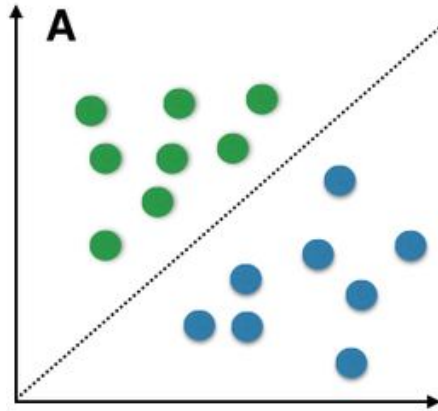


# Leave-one-out



# Classification Quality

- Splitting the data is the first step
- The second one involves computing a score (on unseen samples)



# Confusion matrix

		Predicted				$\Sigma$
		unacc	acc	good	v-good	
Actual	unacc	1154	54	2	0	1210
	acc	94	276	14	0	384
	good	0	44	22	3	69
	v-good	0	25	0	40	65
$\Sigma$	1248	399	38	43	1728	

		Predicted		$\Sigma$
		no	yes	
Actual	no	1364	126	1490
	yes	362	349	711
	$\Sigma$	1726	475	2201

Matrix of correct/incorrect classifications

- Rows = actual
- Columns = predicted
- Correct = diagonal

# Accuracy

TP: true positives

The number of positive instances that are classified as positive

FP: false positives

The number of negative instances that are classified as positive

FN: false negatives

The number of positive instances that are classified as negative

TN: true negatives

The number of negative instances that are classified as negative

Correct classification	Classified as	
	+	-
+	true positives	false negatives
-	false positives	true negatives

$$\text{Acc} = \text{sum}(\text{diag})/\text{sum}(\text{all})$$

# Baselines

- Knowing that we are able to classify with a certain accuracy is **fine**, but is that good/bad?
- **Baselines are crucial** in machine learning - comparing your method against other methods is the most credible way to prove its actual performance.

A simple baseline: Majority class **#most frequent class / all**

		Predicted		$\Sigma$
		no	yes	
Actual	no	1364	126	1490
	yes	362	349	711
$\Sigma$		1726	475	2201

= 68%

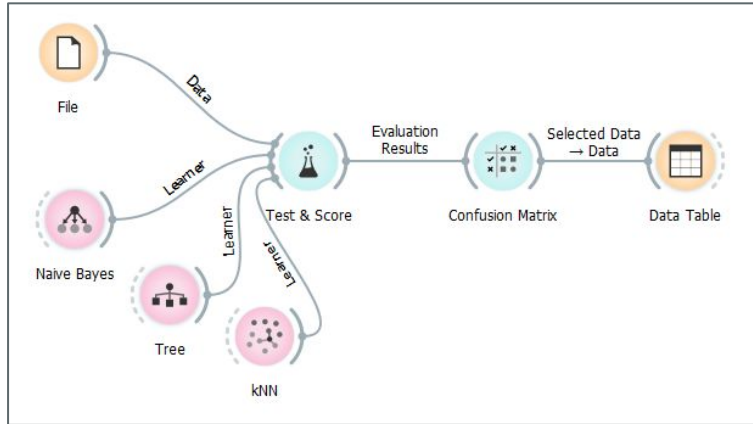


# Class-specific metrics



<b>True Positive Rate</b> or Hit Rate or Recall or Sensitivity or TP Rate	$TP/P$	The proportion of positive instances that are correctly classified as positive
<b>Precision</b> or Positive Predictive Value	$TP/(TP+FP)$	Proportion of instances classified as positive that are really positive
<b>F1 Score</b>	$(2 \times \text{Precision} \times \text{Recall}) / (\text{Precision} + \text{Recall})$	A measure that combines Precision and Recall
<b>Accuracy</b> or Predictive Accuracy	$(TP + TN)/(P + N)$	The proportion of instances that are correctly classified

# Practice time: evaluation and Orange3



## Evaluation methods in Orange

The screenshot shows the 'Sampling' settings for the 'Test & Score' widget. The settings are as follows:

- Cross validation
  - Number of folds: 10
  - Stratified
- Cross validation by feature
- Random sampling
  - Repeat train/test: 10
  - Training set size: 66 %
  - Stratified
- Leave one out
- Test on train data
- Test on test data

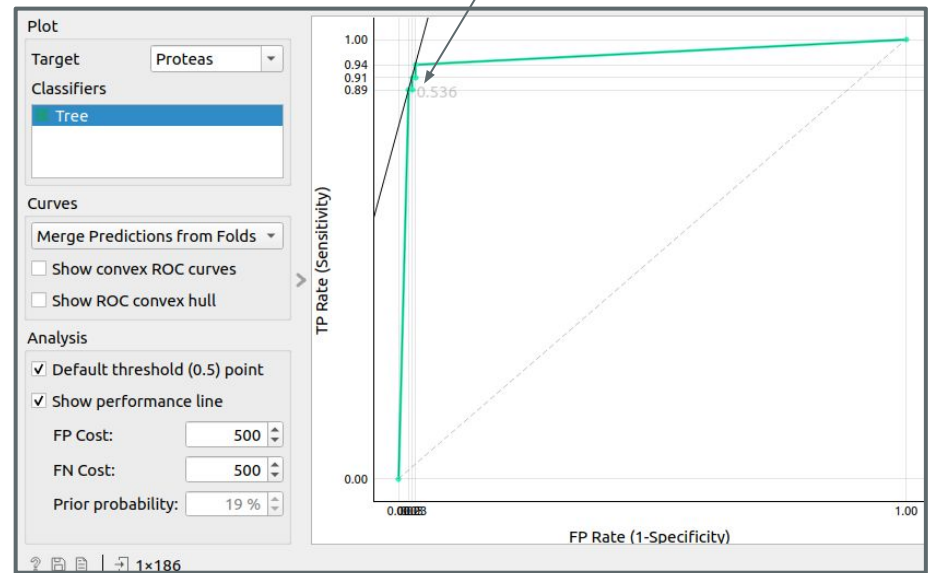
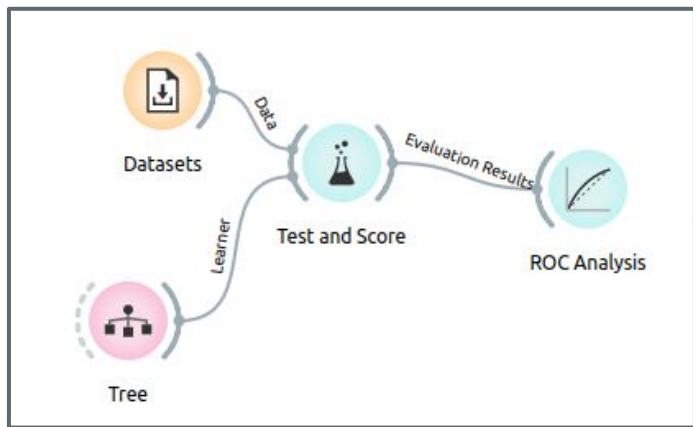
Arrows point from the list of evaluation methods to the corresponding radio buttons in the settings panel.

# ROC curves

**Key point:** Varying discrimination threshold has great impact on classification!

True positive rate =  $\frac{TP}{TP + FN}$

False positive rate =  $1 - \text{Specificity} = \frac{FP}{FP + TN}$

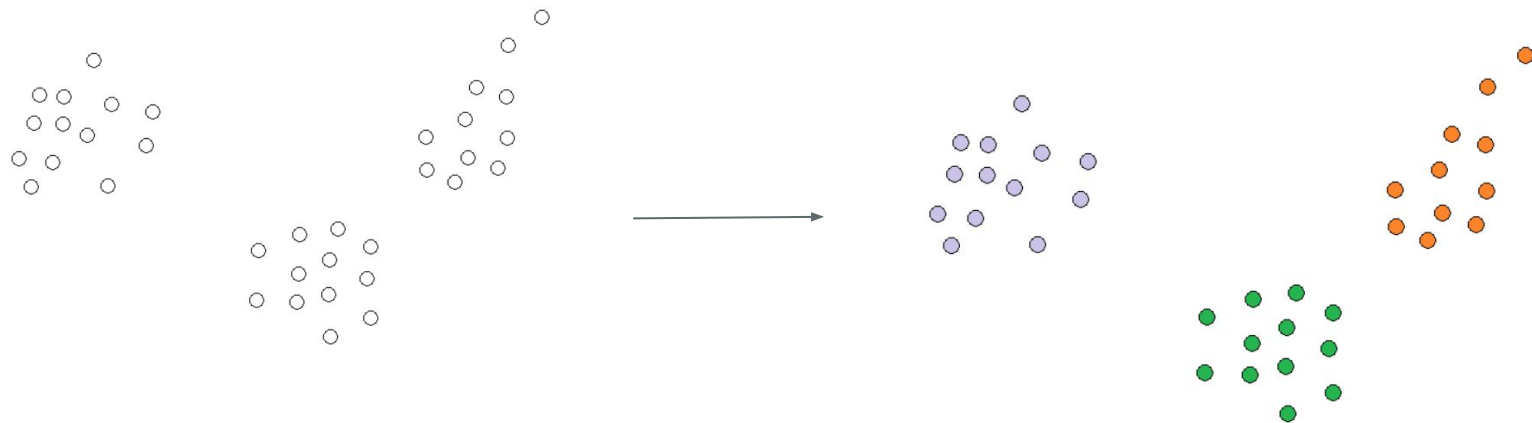


# HW questions

1. For a given classifier, obtain its confusion matrix (Iris data set, 70:30 split)
2. Compute the Precision and Recall for the most frequent class
3. Compute F1
4. Compute the precision of the Majority classifier. What do you observe?

# Unsupervised learning: clustering

# End-goal



# Clustering

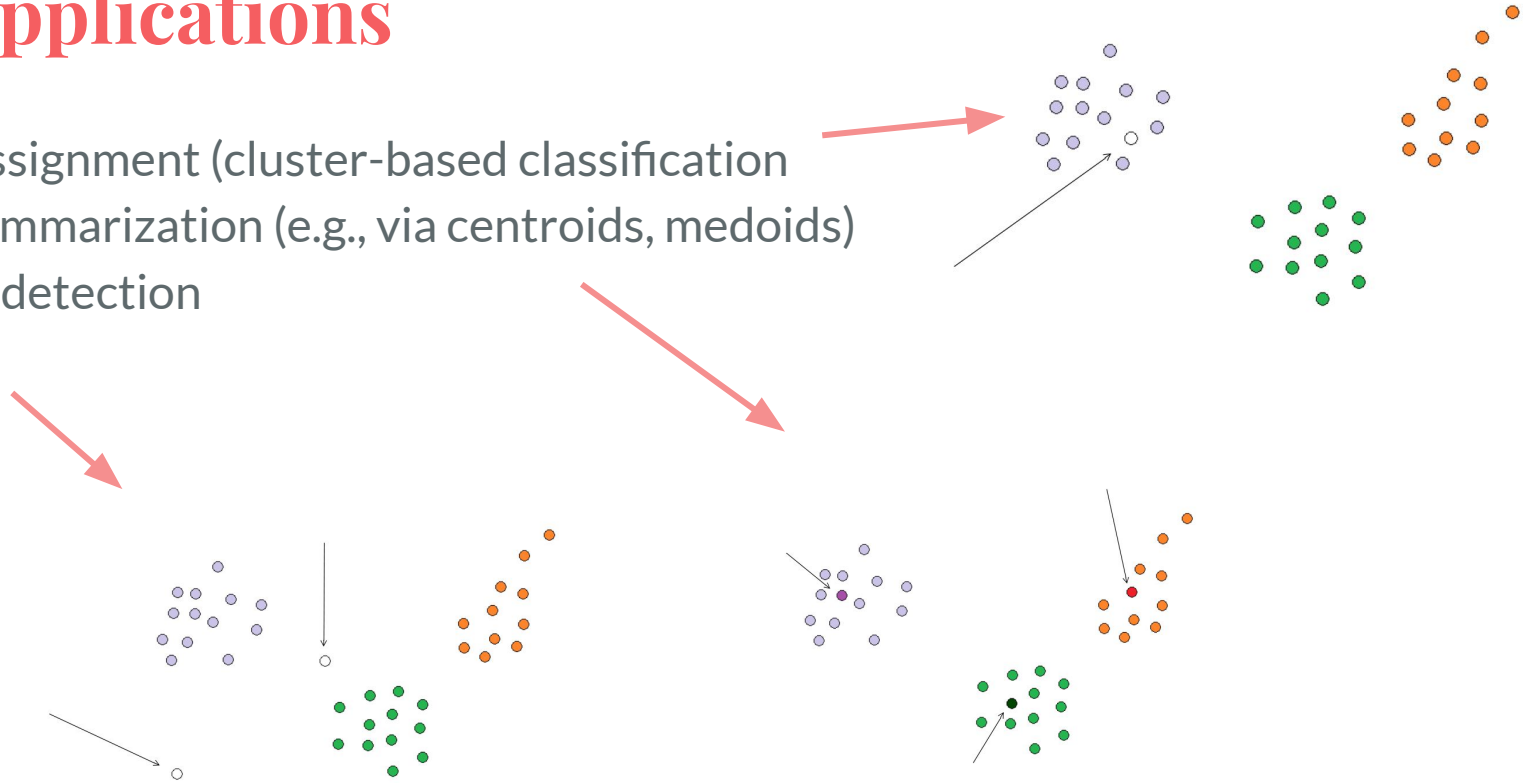
... is the process of grouping the data instances into clusters so that objects within a cluster have high similarity but are very dissimilar to objects in other clusters.

Wish list:

- Identity clusters irrespective of their shapes
- Scalability
- Ability to deal with noisy data
- Insensitivity to the order of input records

# Some applications

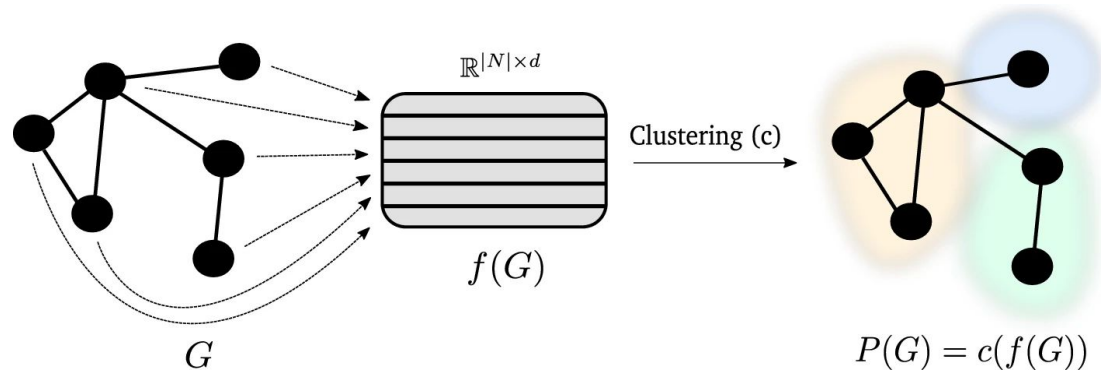
1. Label assignment (cluster-based classification)
2. Data summarization (e.g., via centroids, medoids)
3. Outlier detection





# More applications

1. Customer segmentation and collaborative filtering
2. Text applications
3. Social network analysis



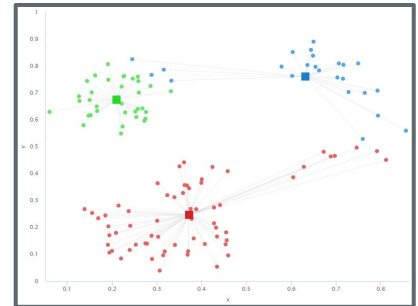
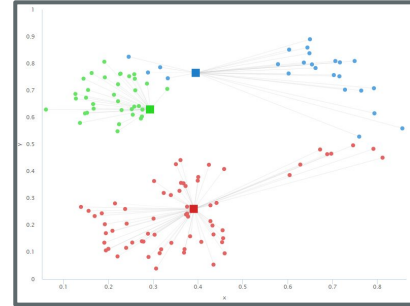
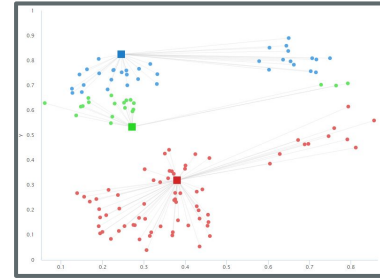
# Clustering algorithm types

- Partitioning-based
  - K-means, k-medoids, k-modes
- Hierarchical
  - Agglomerative
- Grid-based
  - Multi-resolution grid structure
  - Efficient and scalable
- Density based
  - Low/high density regions of space (DBSCAN, OPTICS, DenClue)

# k-Means

1. Choose **k random instances** as cluster centers
2. Assign each instance to its **closest cluster** center
3. Re-compute cluster centers by computing the average (*aka centroid*) of the instances pertaining to each cluster
4. If cluster centers have moved, go back to Step 2
5. (Equivalent termination criterion: stop when assignment of instances to cluster centers has not changed)

Alternatives: *K-medoids*, *K-modes*



# Some properties of k-Means

- The number of clusters  $k$  is fixed in advance
- It is fast, it always converges
- Can converge into a local minima (bad solution because of unlucky start)
- Finds “spherical” shaped clusters
- k-Means will cluster the data even if it can't be clustered (e.g. data that comes from uniform distributions)

# How many clusters?

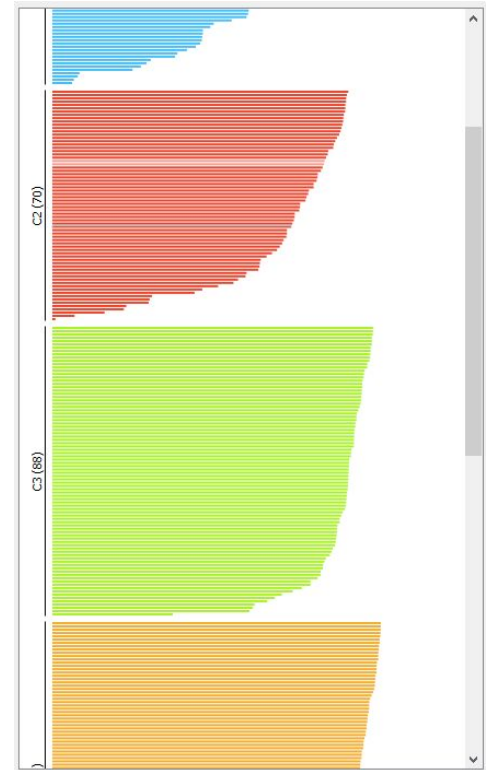
The silhouette value is a measure of how similar an object is to its own cluster (cohesion) compared to other clusters (separation).

- For example  $x_i$ , its silhouette coefficient is  $s_i = (b_i - a_i) / \max(a_i, b_i)$

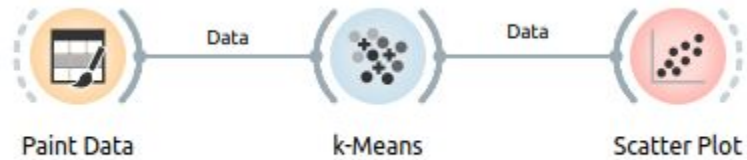
$a_i$  average distance between  $x_i$  to all other examples in its cluster.

$b_i$  average distance between  $x_i$  to the examples in the “closest neighboring” cluster

The overall silhouette coefficient is the average of the data point-specific coefficients.



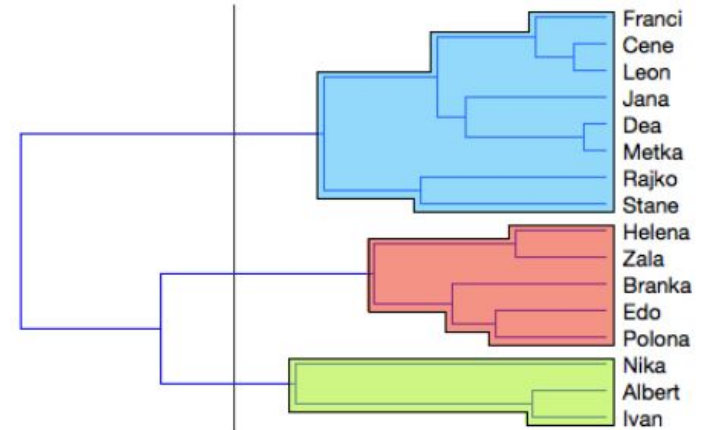
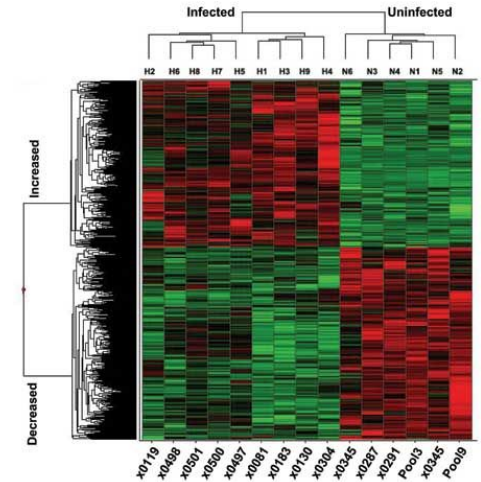
# Practice: Number of clusters and custom data



# Agglomerative clustering

- Start with a collection  $C$  of  $n$  singleton clusters
  - Each cluster contains one data point  $c_i = \{x_i\}$
- Repeat until only one cluster is left:
  - Find a pair of clusters that is closest:  $\min D(c_i, c_j)$
  - Merge the clusters  $c_i$  and  $c_j$  into  $c_i + j$
  - Remove  $c_i$  and  $c_j$  from the collection  $C$ , add  $c_i + j$

Discuss: time&space complexity?



# Linkage functions and metrics

Two main parameters: The metric (e.g., Manhattan, Euclidean etc.),

and linkage:  $D(X, Y) = \min_{x \in X, y \in Y} d(x, y)$

- Single Linkage

$$D(X, Y) = \frac{1}{N_X \times N_Y} \sum_{i=1}^{N_X} \sum_{j=1}^{N_Y} d(x_i, y_j);$$

$x_i \in X, y_j \in Y,$

- Average Linkage

- Ward Linkage

$$ESS(X) = \sum_{i=1}^{N_X} \left| x_i - \frac{1}{N_X} \sum_{j=1}^{N_X} x_j \right|^2$$

- Complete Linkage

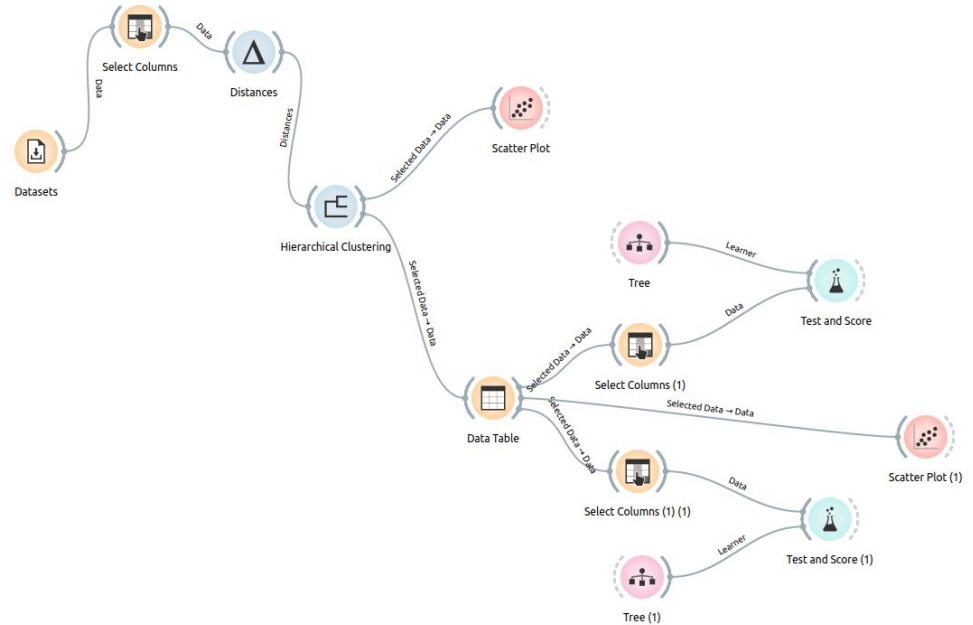
$$D(X, Y) = \max_{x \in X, y \in Y} d(x, y)$$

$$D(X, Y) = ESS(XY) - [ESS(X) + ESS(Y)]$$

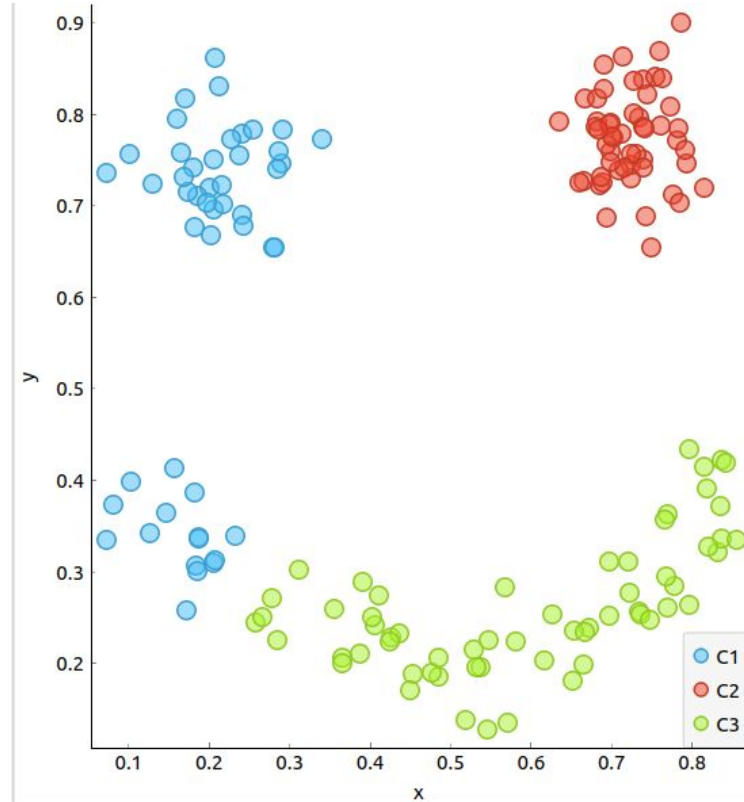


# Practice

- Language bias of clustering algorithms
- The clustering hypothesis



# Practice - algorithmic language bias



# Interesting things to try

1. Write your version of Single-linkage Hierarchical Clustering. Try to skip a step or two during cluster generalization. What do you observe?
2. Implement k-medoids algorithm and try to estimate cluster uncertainty by performing multiple initializations (and implementing their combination)