Logistic Regression

- Probabilistic linear classifier
- Logistic (sigmoid) function f(x)=1/(1+e^{-x})
 - Where $x = w_0 + \sum_i w_i x_i$
 - f(x) = P(C=1 | X)
- $w_0 + \sum_i w_i x_i = 0$ defines a hyperplane where P(C=1|X) = 0.5 and P(C=0|X) = 0.5and $w_0 + \sum_i w_i x_i$ is proportional to the distance from the hyperplane
- Learning
 - no closed form solution optimization, e.g., with gradient descent
 - definition of a cost function (several options); -y log (y') (1-y) log (1-y'); y in {0,1}
 - updating of weights (according to optimization results); $w_j = w_j \alpha \sum_i (y'_i y_i)x_{ij}$ for all instances, multiple times



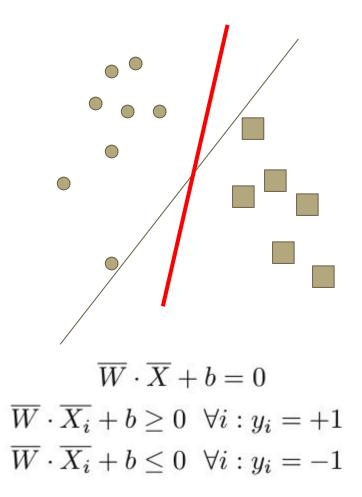
- Linear binary classifier (not probabilistic)
- Extension of linear classifiers to model non-linear decision boundaries
 - Transformation of the feature space using synthetic features of higher order

$$y' = w_0 + w_1x_1 + w_2x_2 + w_3x_1^2 + w_4x_2^2 + w_5x_1x_2$$

- But this brings problems
 - Computational complexity (a lot more parameters to learn, transformation operations)
 - Overfitting
- SVM algorithm deals with these (<u>max. margin & SV</u>, <u>kernel trick & SV</u>)

SVM - max. margin

 Model (linear, *hyperplane*) for separation of data by using the <u>maximal margin</u> principle (MAX: robustness, SV: stability)



- Learning: maximal margin (optimal hyperplane) optimization problem
- Soft margin to allow misclassifications
 - Distance on the wrong side: ξ_i
 - Parameter *C* (misclassification cost) set with experimentation!
 - **Penalty:** $\mathbf{C} \cdot \boldsymbol{\xi}_{i}^{r}$

SVM - kernel trick

- Use of higher dimensions for linearly non-separable data
 - o <u>https://www.youtube.com/watch?v=3liCbRZPrZA</u>
- Learning (optimization) involves dot products in the term to maximize:

$$L_D = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \lambda_i \lambda_j y_i y_j \overline{X_i} \cdot \overline{X_j}$$

Dot product is needed, (not feature values)

~similarity

classification too:

We can avoid representing W

$$F(\overline{Z}) = \operatorname{sign}\{\overline{W} \cdot \overline{Z} + b\} = \operatorname{sign}\{(\sum_{i=1}^{n} \lambda_i y_i \overline{X_i} \cdot \overline{Z}) + b\}$$

SVM - kernel trick, here it is

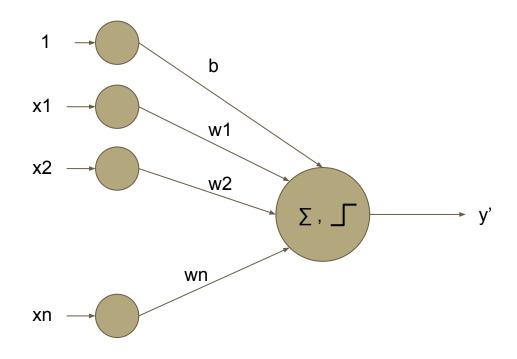
- We do not need the feature values, just dot products
- Transformation would mean: $\Phi(x_i) \cdot \Phi(x_i)$

calculation of transformations, then the lengthy dot products...

- Instead, we can use a function such that: $K(x_i, x_j) = \Phi(x_j) \cdot \Phi(x_j)$
 - And $K(x_i, x_j)$ is in original space!
 - EXAMPLE !
 - We can only calculate kernels (polynomial, Gaussian RBF, ...)
 - Simetric, positive semi-definite; similarity ; even for strings, graphs
 - \circ The mapping Φ can now be only implicitly used

Neural networks - perceptron

• Inspired by (simulation of) the human nervous system



$$y = sign(\sum_{i} w_i x_i + b)$$

Learning (iterative process):

- Initialize weights
- For each training item (**x**,**y**)

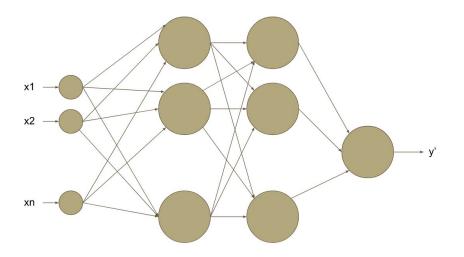
 \circ y' = f(w,x)

$$w_{i}^{'} = w_{i} + \eta(y_{i}-y_{i}^{'})x_{i}$$

• Until convergence

- Can learn (converge) in linearly separable situations
- Finds (some!) linear separation

Neural networks with hidden layers



- Very powerful in capturing arbitrary functions
 - having non-linear activation functions; careful selection to facilitate learning
- Automatic generation of (higher-level) features!
 - last level is similar to logreg on generated (relevant) high-level features, not all quadratic, cubic, ... which easily go into hundreds of thousands.
- Drawbacks
 - computationally demanding learning (recently alleviated)
 - more layers more power more prone to overfitting
 - black-box models

Neural network - use (forward propagation)

Use of a neural network

$$h_{1}^{(2)} = f(w_{11}^{(1)}x_{1} + w_{12}^{(1)}x_{2} + \dots + w_{1n}^{(1)}x_{n})$$

$$h_{2}^{(2)} = f(w_{21}^{(1)}x_{1} + w_{22}^{(1)}x_{2} + \dots + w_{2n}^{(1)}x_{n})$$

$$\dots$$

$$h_{m}^{(2)} = f(w_{m1}^{(1)}x_{1} + w_{m2}^{(1)}x_{2} + \dots + w_{mn}^{(1)}x_{n})$$

$$y' = f(w_{11}^{(2)}h_{1}^{(2)} + w_{12}^{(2)}h_{2}^{(2)} + \dots + w_{1m}^{(2)}h_{n}$$

Neural networks - learning

- Two things to learn:
 - Structure: expert knowledge and experimentation
 - Parameters/weights : <u>backpropagation</u> (and other optimization approaches)
 - Gradient descent (consequence: step \rightarrow sigmoid; error 0/1 \rightarrow (y-y')²)
 - Optimum can be local !
 - Can be done in a batch or online mode
 - Overfitting problem stop on check with holdout, ...
 - Computationally demanding
 - Nice explanation of the procedure in the Weka book CHECK!
 - Activation function selection was not random ;)

Ensemble methods

- Combine results of multiple classifiers
 - Different learners
 - Different training data subsets
 - Combined predictions
 - averaging
 - weighted voting
 - model of combination
- Helps tackling error components
 - Bias
 - Model assumptions (e.g., linear separation)
 - Consistently incorrect for some instances
 - Variance
 - Data variations leading to very different models (~ overfitting)
 - Inconsistently classified data
 - Noise
 - Intrinsic error in target class
 - Some algorithms are more affected, some less

Bagging

- Single learning algorithm
- *k* data samples with replacement
- *k* learned (same kind) classifiers
- Majority vote
- Reduces variance (makes sense for low bias learners, e.g. deep trees)
- Models are independent, can be built in parallel

Boosting

- Single learning algorithm
- Weighted training instances
 - Adapted learning
 - Weighted data sampling
- Iterative reweighting according to classifier performance
- Focus on misclassified instances in next iteration (increased weights)
 - Various increase approaches and termination criteria
- Aggregation of weighted (according to performance) predictions
- Reduces overall bias (to be used with simple, high bias, models)
- Reduction of variance depends on intensity of reweighting scheme
 - No reweighting in iterations == bagging
- <u>Sensitive to noise</u> (training can focus on bad data!)
- Models depend on previous ones, sequential process

Stacking

- Combination of predictions with another machine learned model
- Two level classification, two data subsets
- *k* classifiers (bagged, boosted or from different learners) learned on the first subset
- Their outputs on second subset are <u>k new features</u>
- Second level classifier is trained on
 - new feature space (of size *k*), or
 - combined feature space (old+new)



- Similar as bagging with decision trees, but promotes more diverse trees
 - Decision trees in bagging tend to be similar
- Randomness at splits:
 - A random subset of attributes
 - Often advised: log₂(#all_atribs)+1
- Usually no or minimal pruning
- Also bootstrapped data samples (as in bagging)
- Majority vote
- Efficient (less attributes considered at splits)
- Resistant to noise, outliers and overfitting



- Similar as bagging with decision trees, but promotes more diverse trees
 - Decision trees in bagging tend to be similar
- Randomness at splits:
 - A random subset of attributes
 - Often advised: log₂(#all_atribs)+1
- Usually no or minimal pruning
- Also bootstrapped data samples (as in bagging)
- Majority vote
- Efficient (less attributes considered at splits)
- Resistant to noise, outliers and overfitting

Gradient boosted trees

- Construct a (regression) tree and let the residuals (y-F(x)) become a new target for another model in the iteration
- Next model learns the residuals of the first one
 - Using original features and the new target
- Taking the two models together we get a better prediction
- Repeat *m* times, until stopping criterion...
- In fact: a gradient of a differentiable loss function is usually modelled instead of actual residuals (added parameter: step size)
- Sensitive to noise
- Sequential (cannot run in parallel)

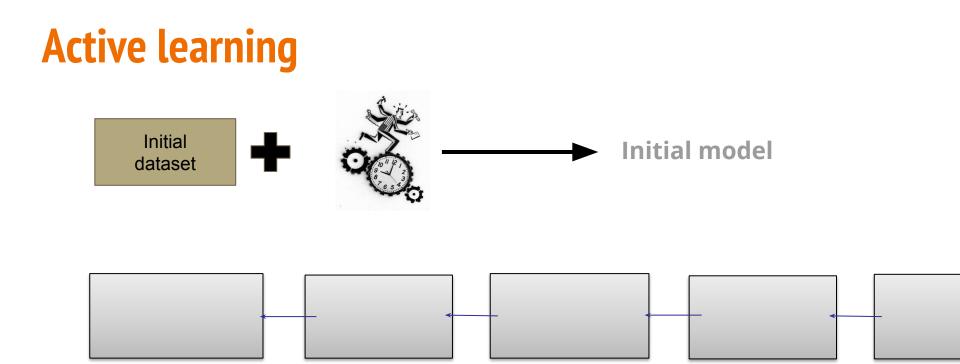
Gradient boosted trees

- Construct a (regression) tree and let the residuals (y-F(x)) become a new target for another model in the iteration
- Next model learns the residuals of the first one
 - Using original features and the new target
- Taking the two models together we get a better prediction
- Repeat *m* times, until stopping criterion...
- In fact: a gradient of a differentiable loss function is usually modelled instead of actual residuals (added parameter: step size)
- Sensitive to noise

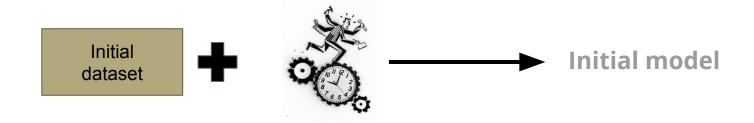
 \rightarrow ESA challenge example

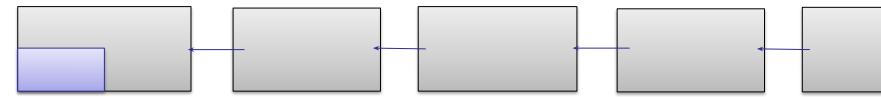
• Sequential (cannot run in parallel)

- Labels are sometimes hard or expensive to get
 - Time restrictions in dynamic settings
- AL aims at getting the most of information with the least amount of labels
- Components
 - Querying system : selects the instances to be labelled
 - Oracle : provides labels
- Querying strategies
 - Highest uncertainty regions (danger: querying in low data quality areas)
 - Expected error of variance reduction
 - Representativeness
 - Equal representativeness of regions (weighted by density)
 - And many others and their mixtures...



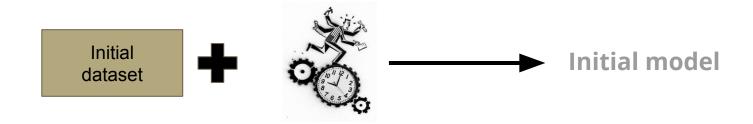
Active learning Initial Initial model dataset 0 0 • ٥ 0 **Initial model**

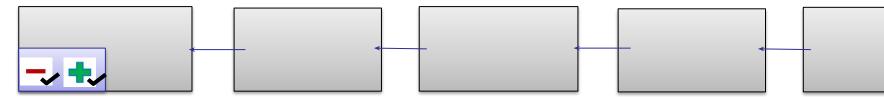






Initial model







Initial model

Active learning Initial **Initial model** dataset 0 0 0 0 Updated Initial model model

