Data Mining and Knowledge Discovery: Practice Notes

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Keywords

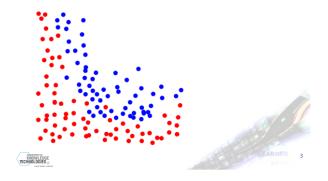


- Data
 - Attribute, example, attribute-value data, target variable, class, discretization
- Algorithms
 - Decision tree induction, entropy, information gain, overfitting, Occam's razor, model pruning, naïve Bayes classifier, KNN, association rules, support, confidence, numeric prediction, regression tree, model tree, heuristics vs. exhaustive search, predictive vs. descriptive DM
- Evaluation
 - Train set, test set, accuracy, confusion matrix, cross validation, true positives, false positives, ROC space, AU error, precision, recall

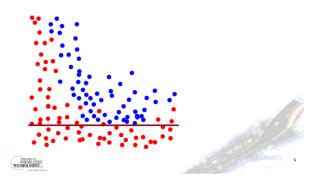


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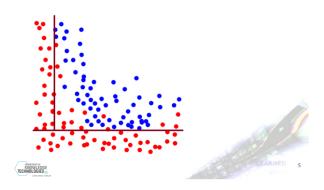
DT induction graphically



DT induction graphically

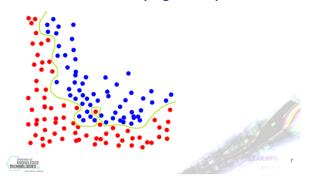


DT induction graphically

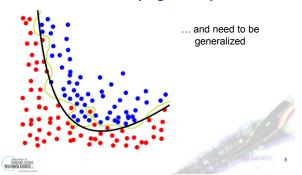


DT induction graphically

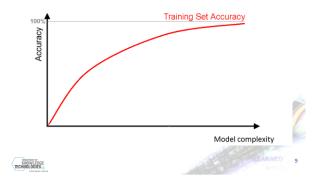
Models with other language biases can also overfit (e.g. SVM)



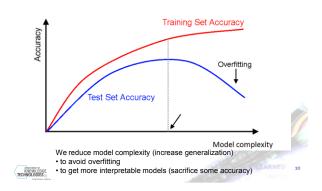
Models with other language biases can also overfit (e.g. SVM)



Model complexity and performance on train set



Performance on train and test set



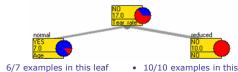
Occam's raisor

KNOWLEDGE TECHNOLOGIES

 Suppose there exist two explanations for a phenomena. In this case, the simpler one is usually better.



Prediction confidence



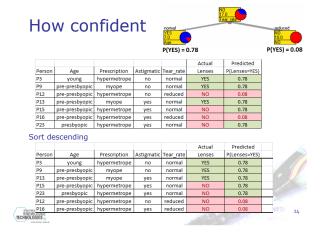
- 6/7 examples in this leaf belong to the class Lenses=YES
- 1/7 belongs to the class Lenses=NO

P(YES) = 6/7 = 0.86 $P_{Laplace}(YES) = \frac{6+1}{7+2} = 0.78$

- 10/10 examples in this leaf belong to class Lenses=NO
- P(YES) = 0/10 = 0 $P_{Laplace}(YES) = \frac{0+1}{10+2} = 0.08$

KNOWLEDGE TECHNOLOGIES * Laplace probability estimate is explained at "Naïve Bayes".

How confident P(YES) = 0.78P(YES) = 0.08Astigmatic Tear Rate hypermetrope P3 young no normal YES P9 YES pre-presbyopi myope no normal hypermetrope P12 pre-presbyopio no reduced P13 pre-presbyopio yes normal YFS P15 pre-presbyopio hypermetrope yes normal NO pre-presbyopic hypermetrope reduced yes P23 presbyopic Assign to each example in the test set a confidence score of assigning it to the class "Lenses=YES".

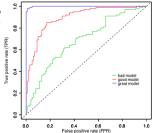


ROC curve and AUC

- Receiver Operating Characteristic curve (or ROC curve) is a plot of the true positive rate (TPr=Sensitivity=Recall) against the false positive rate (FPr) for different possible cutpoints.
- It shows the tradeoff between sensitivity and specificity (any increase in sensitivity will be accompanied by a decrease in specificity).
- . The closer the curve to the top left corner, the more accurate the classifier.
- The diagonal represents a baseline classifier.

KNOWLEDGE TECHNOLOGIES

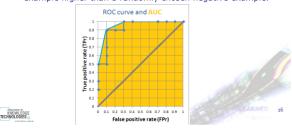
* Use Laplace estimate



P(YES) = 0.08

AUC - Area Under (ROC) Curve

- Performance is measured by the area under the ROC curve (AUC). An area of 1 represents a perfect classifier; an area of 0.5 represents a worthless classifier.
- The area under the curve (AUC) is equal to the probability that a classifier will rank a randomly chosen positive example higher than a randomly chosen negative example.



How confident P(YES) = 0.78

					Actual	Predicted
Person	Age	Prescription	Astigmatic	Tear_rate	Lenses	P(Lenses=YES)
P3	young	hypermetrope	no	normal	YES	0.78
P9	pre-presbyopic	myope	no	normal	YES	0.78
P13	pre-presbyopic	myope	yes	normal	YES	0.78
P15	pre-presbyopic	hypermetrope	yes	normal	NO	0.78
P23	presbyopic	hypermetrope	yes	normal	NO	0.78
P12	pre-presbyopic	hypermetrope	no	reduced	NO	0.08
P16	pre-presbyopic	hypermetrope	yes	reduced	NO	0.08

Possible classifiers:

100 % confident \rightarrow TP=0, FP=0 \rightarrow TPr= 0, FPr=0

78 % confident \rightarrow TP=3, FP=2 \rightarrow TPr= 3/3 = 1, FPr= 2/4 = 0.5

8 % confident \rightarrow TP=3, FP=4 \rightarrow TPr= 3/3 = 1, FPr= 4/4 = 1 0 % confident \rightarrow TP=3, FP=4 \rightarrow TPr= 3/3 = 1, FPr= 4/4 = 1 TPr = |correctly classified positives| / |all positives| FPr = |negatives classified as positives| / |all negatives| KNOWLEDGE TECHNOLOGIES

Classifier to ROC

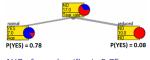
Possible classifiers:

100 % confident \rightarrow TP=0, FP=0 \rightarrow TPr= 0, FPr=0

78 % confident \rightarrow TP=3, FP=2 \rightarrow TPr= 3/3 = 1, FPr= 2/4 = 0.5

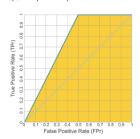
8 % confident \rightarrow TP=3, FP=4 \rightarrow TPr= 3/3 = 1, FPr= 4/4 = 1

0 % confident \rightarrow TP=3, FP=4 \rightarrow TPr= 3/3 = 1, FPr= 4/4 = 1



AUC of our classifier is 0.75. An AUC close to 0.5 is a bad AUC.

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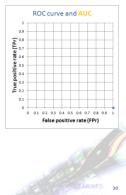


ROC curve and AUC

L (curv	e an	a A	UC			
		Confidence					
		classifier					
	Actual class	forclass Y	FP	TP	FPr	TPr	
P1	Υ	1					
P2	Υ	1					
P3	Υ	0.95					
P4	Υ	0.9					
P5	Υ	0.9					
P6	N	0.85					
P7	Υ	0.8					
P8	Υ	0.6					
P9	Υ	0.55					
P10	Υ	0.55					
P11	N	0.3					
P12	N	0.25					
P13	Υ	0.25					
P14	N	0.2					
P15	N	0.1				. 16	
P16	N	0.1				-63	7
P17	N	0.1				1/201	
P18	N	0			1333		(A)
P19	N	0					EARNED 19
P20	N	0		400	Delignary of		MEDIS

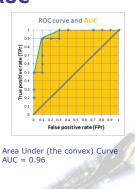
ROC curve and AUC

	Actual class	Confidence classifier forclass Y	FP	TP	FPr	TPr
P1	Υ	1	0	2	0	0.2
P2	Υ	1	0	2	0	0.2
P3	Υ	0.95	0	3	0	0.3
P4	Υ	0.9	0	5	0	0.5
P5	Υ	0.9	0	5	0	0.5
P6	N	0.85	1	5	0.1	0.5
P7	Υ	0.8	1	6	0.1	0.6
P8	Υ	0.6	1	7	0.1	0.7
P9	Υ	0.55	1	9	0.1	0.9
P10	Υ	0.55	1	9	0.1	0.9
P11	N	0.3	2	9	0.2	0.9
P12	N	0.25	3	9	0.3	0.9
P13	Υ	0.25	3	10	0.3	
P14	N	0.2	4	10	0.4	
P15	N	0.1	7	10	0.7	
P16	N	0.1	7	10	0.7	
P17	N	0.1	7	10	0.7	- 1
P18	N	0	8	10	0.8	- :
P19(NOV	N	0	9	10	0.9	- :
P20	N	0	10	10	1	- :



ROC curve and AUC

		Confidence classifier		
	Actual class	forclass Y	FPr	TPr
P1	Υ	1	0	0.2
P2	Υ	1	0	0.2
P3	Υ	0.95	0	0.3
P4	Υ	0.9	0	0.5
P5	Υ	0.9	0	0.5
P6	N	0.85	0.1	0.5
P7	Υ	0.8	0.1	0.6
P8	Υ	0.6	0.1	0.7
P9	Υ	0.55	0.1	0.9
P10	Υ	0.55	0.1	0.9
P11	N	0.3	0.2	0.9
P12	N	0.25	0.3	0.9
P13	Υ	0.25	0.3	1
P14	N	0.2	0.4	1
P15	N	0.1	0.7	1
P16	N	0.1	0.7	1
P17	N	0.1	0.7	1
P18	N	0	0.8	1
P19 KN0	N	0	0.9	1
P20	N	0	1	1



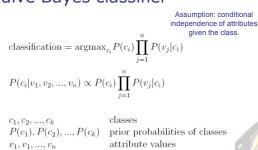
Predicting with Naïve Bayes

Given

- Attribute-value data with nominal target variable Induce
- Build a Naïve Bayes classifier and estimate its performance on new data



Naïve Bayes classifier





Naïve Bayes classifier



Assumption: conditional independence of attributes given the class.

Will the spider catch these two ants?

- Color = white, Time = night
- Color = black, Size = large, Time = day

Color	Size	Time	Caught
black	large	day	YES
white	small	night	YES
black	small	day	YES
red	large	night	NO
black	large	night	NO
white	large	night	NO





Naïve Bayes classifier -example

Color	Size	Time	Caught
black	large	day	YES
white	small	night	YES
black	small	day	YES
red	large	night	NO
black	large	night	NO
white	large	night	NO

$$v_1$$
 = "Color = white"
 v_2 = "Time = night"
 c_1 = YES
 c_2 = NO

$$\begin{split} P(C_1|v_1,v_2) &= \\ &= P(\text{YES}|C = w, T = n) \\ &= P(\text{YES}) \cdot P(C = w|\text{YES}) \cdot P(T = n|\text{YES}) \\ &= \frac{1}{2} \cdot \frac{1}{3} \cdot \frac{1}{3} \\ &= \frac{1}{18} \end{split}$$

$$\begin{split} P(C_2|v_1,v_2) &= & -P(\text{NO}|C = w, T = n) \\ &= & P(\text{NO}|C = w, T = n) \\ &= & P(\text{NO}) \cdot P(C = w|\text{NO}) \cdot P(T = n|\text{NO}) \\ &= & \frac{1}{2} \cdot \frac{1}{3} \cdot 1 \\ &= & \frac{1}{6} \end{split}$$

KNOWLEDGE TECHNOLOGIES

Estimating probability

Relative frequency

- P(e) = |e| /n
- A disadvantage of using relative frequencies for probability estimation arises with small sample sizes, especially if they are either very close to zero, or very close to one.
- In our spider example: P(Time=day|Class=NO) = = 0/3 = 0

 $|e|\dots$ number times an event e happened $n\dots$ number of trials

n ... number of trials
k ... number of possible outcomes



Relative frequency vs. Laplace estimate

Relative frequency

- P(c) = n(c) /N
- A disadvantage of using relative frequencies for probability estimation arises with small sample sizes, especially if they are either very close to zero, or very close to one.
- In our spider example: P(Time=day|caught=NO) = = 0/3 = 0

n(c) ... number of examples where c is true N ... number of all examples k ... number of possible events

Laplace estimate

- Assumes uniform prior distribution over the probabilities for each possible event
- P(c) = (n(c) + 1) / (N + k)
- In our spider example: P(Time=day|caught=NO) = (0+1)/(3+2) = 1/5
- With lots of evidence approximates relative frequency
- If there were 300 cases when the spider didn't catch ants at night: P(Time=day|caught=NO) = (0+1)/(300+2) = 1/302 = 0.003
- With Laplace estimate probabilities can never be 0.

K-fold cross validation

- 1. The sample set is partitioned into K subsets ("folds") of about equal size
- A single subset is retained as the validation data for testing the model (this subset is called the "testset"), and the remaining K - 1 subsets together are used as training data ("trainset").
- 3. A model is trained on the trainset and its performance (accuracy or other performance measure) is evaluated on the testset
- 4. Model training and evaluation is repeated K times, with each of the K subsets used exactly once as the testset.
- 5. The average of all the accuracy estimations obtained after each iteration is the resulting accuracy estimation.







Discussion

- Compare naïve Bayes and decision trees (similarities and differences) .
- Compare cross validation and testing on a separate test set.
- 3. Why do we prune decision trees?
- 4. What is discretization.
- 5. Why can't we always achieve 100% accuracy on the training set?
- ${\it 6.} \quad {\it Compare Laplace estimate with relative frequency}.$
- Why does Naïve Bayes work well (even if independence assumption is clearly violated)?
- 8. What are the benefits of using Laplace estimate instead of relative frequency for probability estimation in Naïve Bayes?





